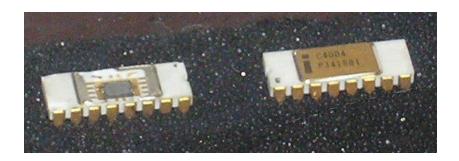
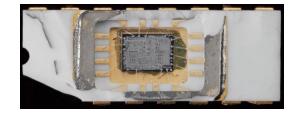
CSCI 210: Computer Architecture Lecture 25: Data Path 2

Stephen Checkoway Slides from Cynthia Taylor

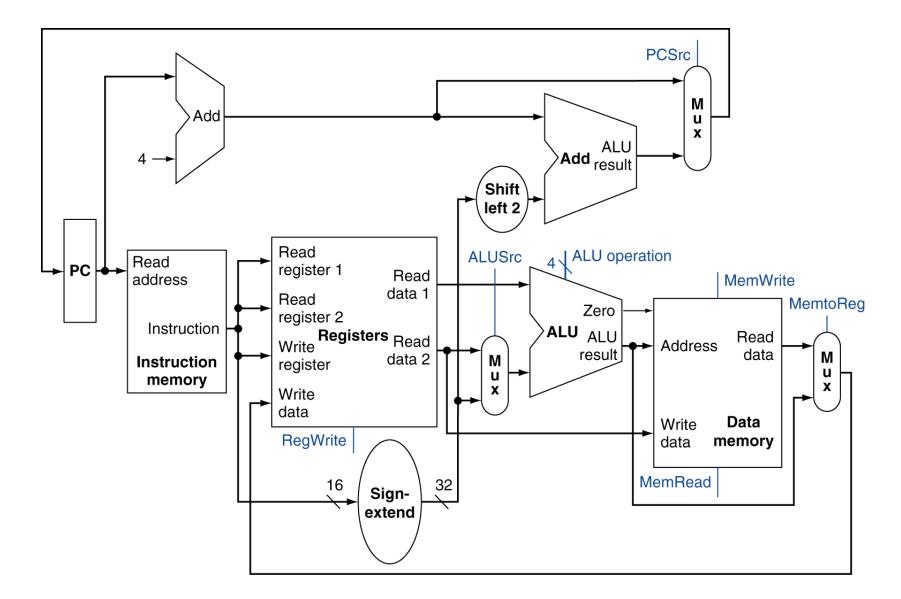
CS History: Intel 4004

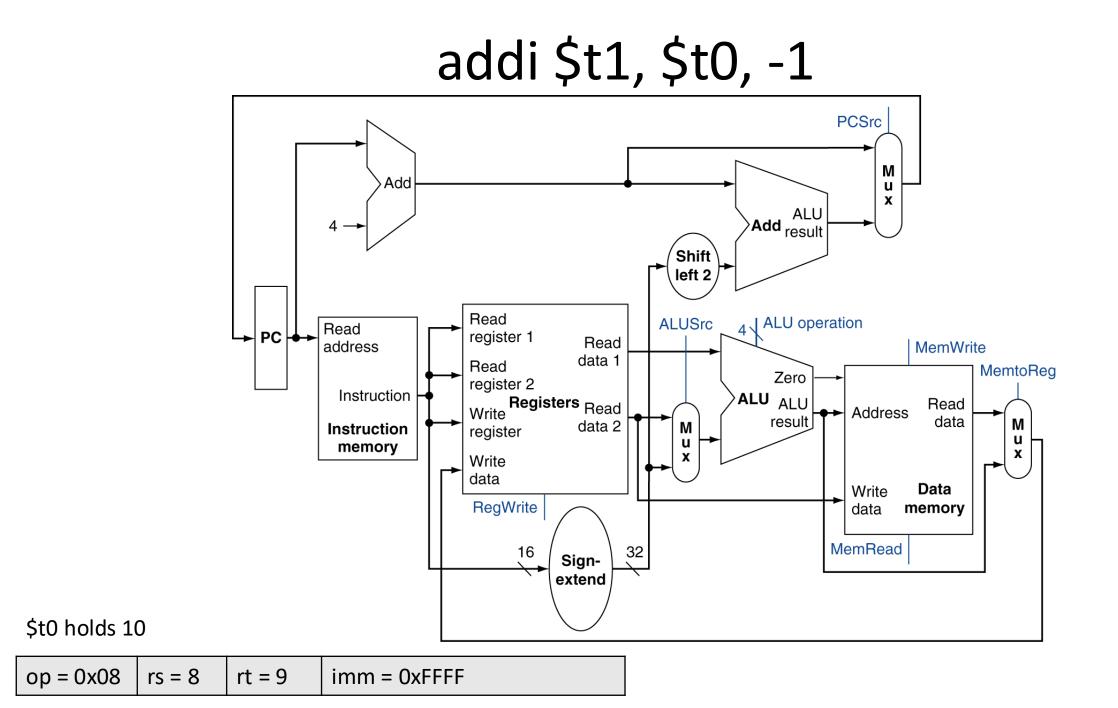




- First commercially available microprocessor (single chip with both data processing logic and control)
- Released in 1971
- Had 12-bit addresses, 8-bit instructions, and 4-bit data words
- 16 4-bit registers
- Designed for Binary-Coded Decimal, in which every decimal digit is stored as a 4-bit value
 - Still present in x86

Datapath (still simplified a bit)

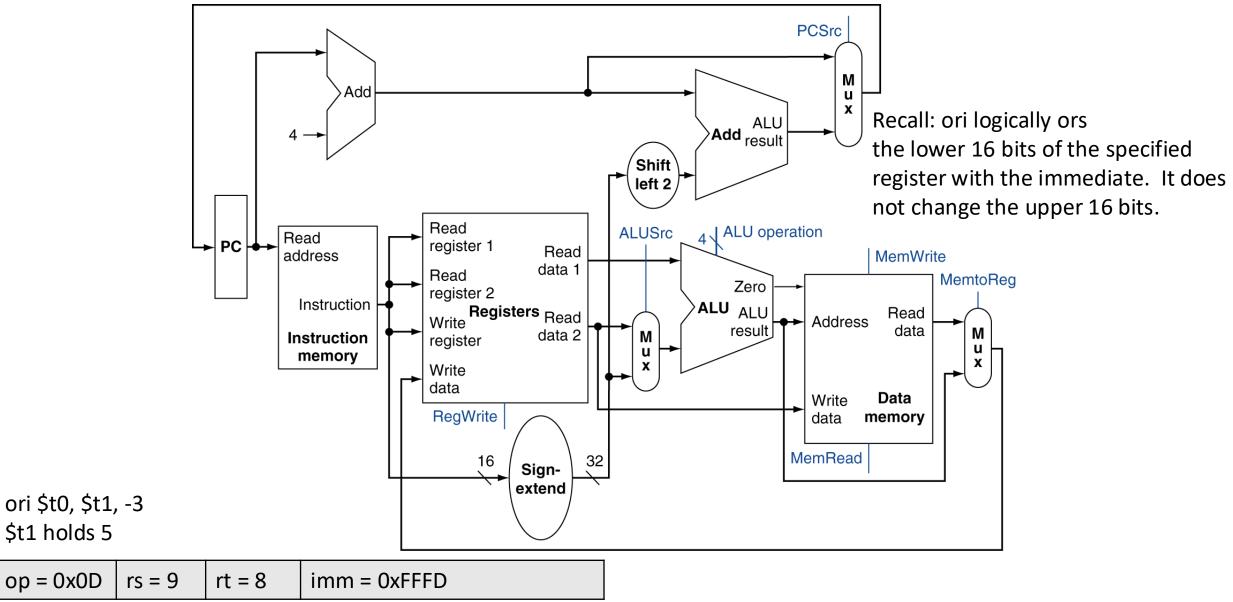




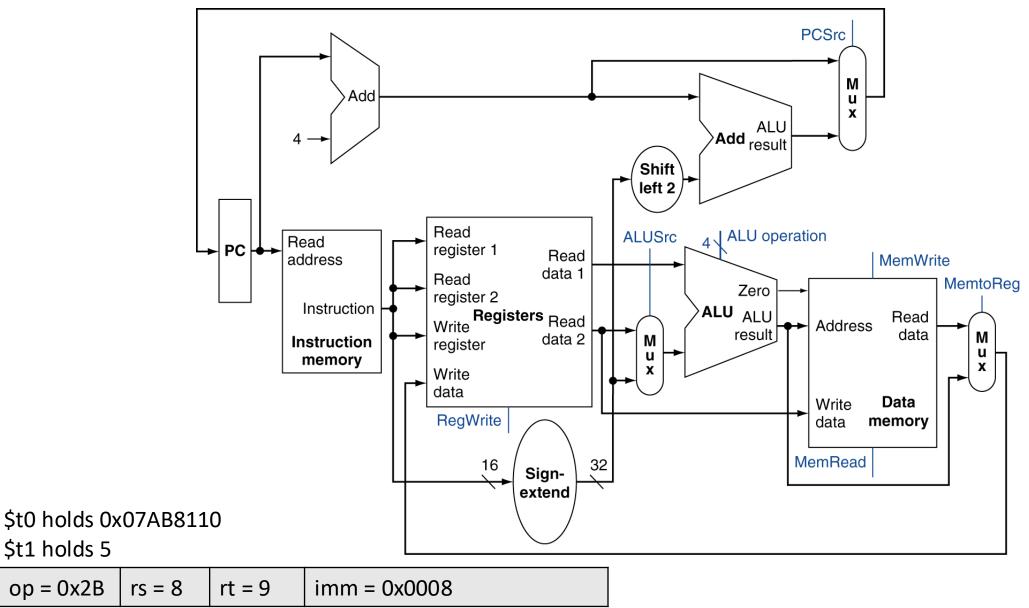
What do we need to add to support ori?

\$t1 holds 5

op = 0x0D



sw \$t1, 8(\$t0)



\$t1 holds 5

op = 0x2B

Composing the Elements

- Data path does an instruction in one clock cycle
 - Each data path element can only do one function at a time
 - Hence, we need separate instruction and data memories, ALU and adders, etc
- Use multiplexers where alternative data sources are used for different instructions
 - Each multiplexer will need select inputs to choose which input to use as the output

Key Points

- CPU is just a collection of state and combinational logic
- We just designed a very rich processor, at least in terms of functionality
- ET = IC * CPI * Cycle Time
 - Where cycle time is determined by how much work the processor has to do each clock cycle for one iteration of fetch, decode, execute

Reading

- Next lecture: Control Path
 - Section 5.4